

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
```

```
{
    int freq[MAXPAROLA]; /* vettore di contatori
    delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;
```

```
for(i=0; i<MAXPAROLA; i++)
    freq[i]=0;
```

```
if(argc != 2)
{
    fprintf(stderr, "ERRORE, serve un parametro con il nome del file\n");
    exit(1);
}
```

```
f = fopen(argv[1], "r");
if(f==NULL)
{
    fprintf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
    exit(1);
}
```

```
while( fgets( riga, MAXRIGA, f ) != NULL )
```



Processes

Theoretical Aspects

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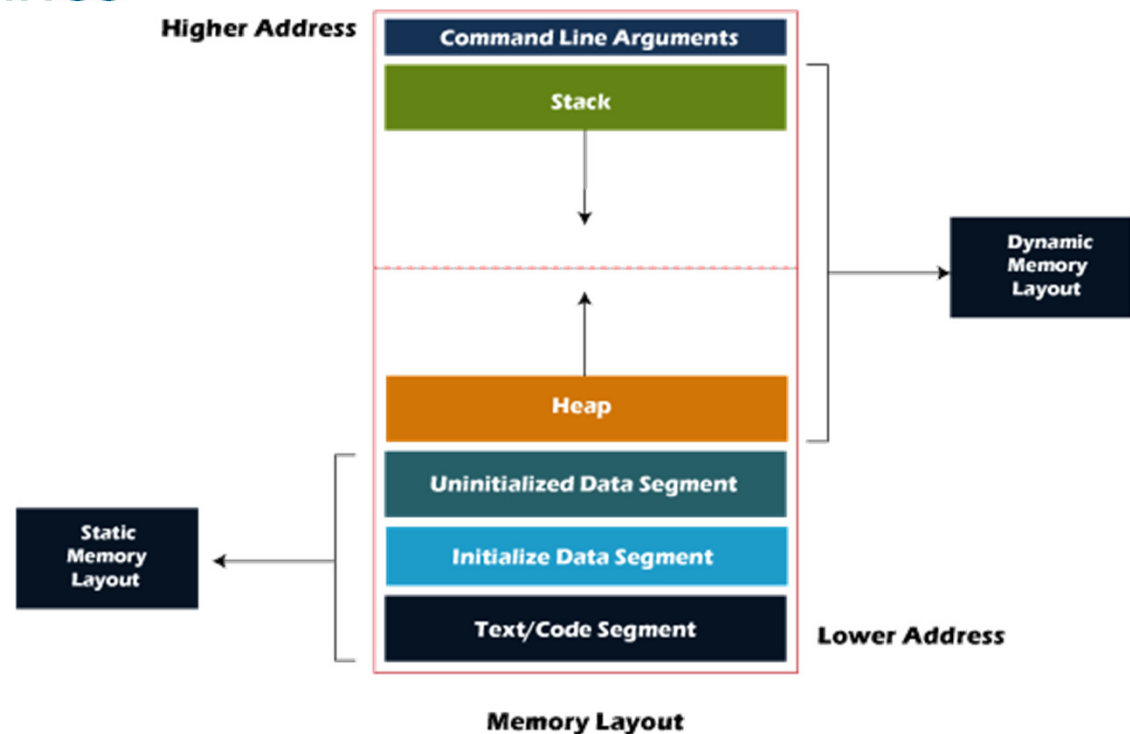
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Program

- ❖ **Algorithm:** a logical procedure that in a finite number of steps solves a problem
- ❖ **Program:** formal expression of an algorithm by means of a programming language
 - Sequence of code lines
 - Static entity



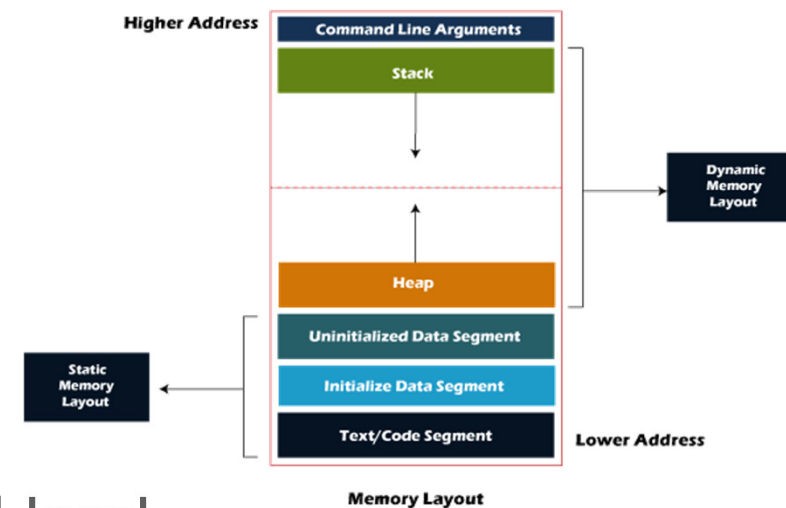
Process

❖ **Process:** a **sequence** of operations performed by a program in execution on a given set of input data.

➤ Dynamic entity

➤ Program in execution (running)

- Text area (executable code)
- Data area (global variables)
- Stack (function parameters and local variables)
- Heap (dynamic variables allocated during the process execution)
- Registers (Program counter, stack pointer, etc.)



Process Control Block (PCB)

Process Control
Block (PCB)

- ❖ The kernel stores for each process a set of data, e.g.,
 - The process state
 - New, Ready, Running, Waiting, Terminated
 - Copy of the CPU registers
 - Their number and type is hardware-dependent
 - The program counter
 - Address of the next instruction to be executed

pointer	process state
process number	
program counter	
registers	
memory limits	
list of open files	
⋮	

Process Control Block (PCB)

- Data useful for CPU scheduling
 - Priority, pointers to queues, etc.
- Data useful for memory management
 - Base register, Limit register, Segment and paging registers, etc.
- Signal table
 - signal handlers
- Various administration data
 - CPU usage, limits, etc.
- I/O status information
 - I/O device list, open files, etc.

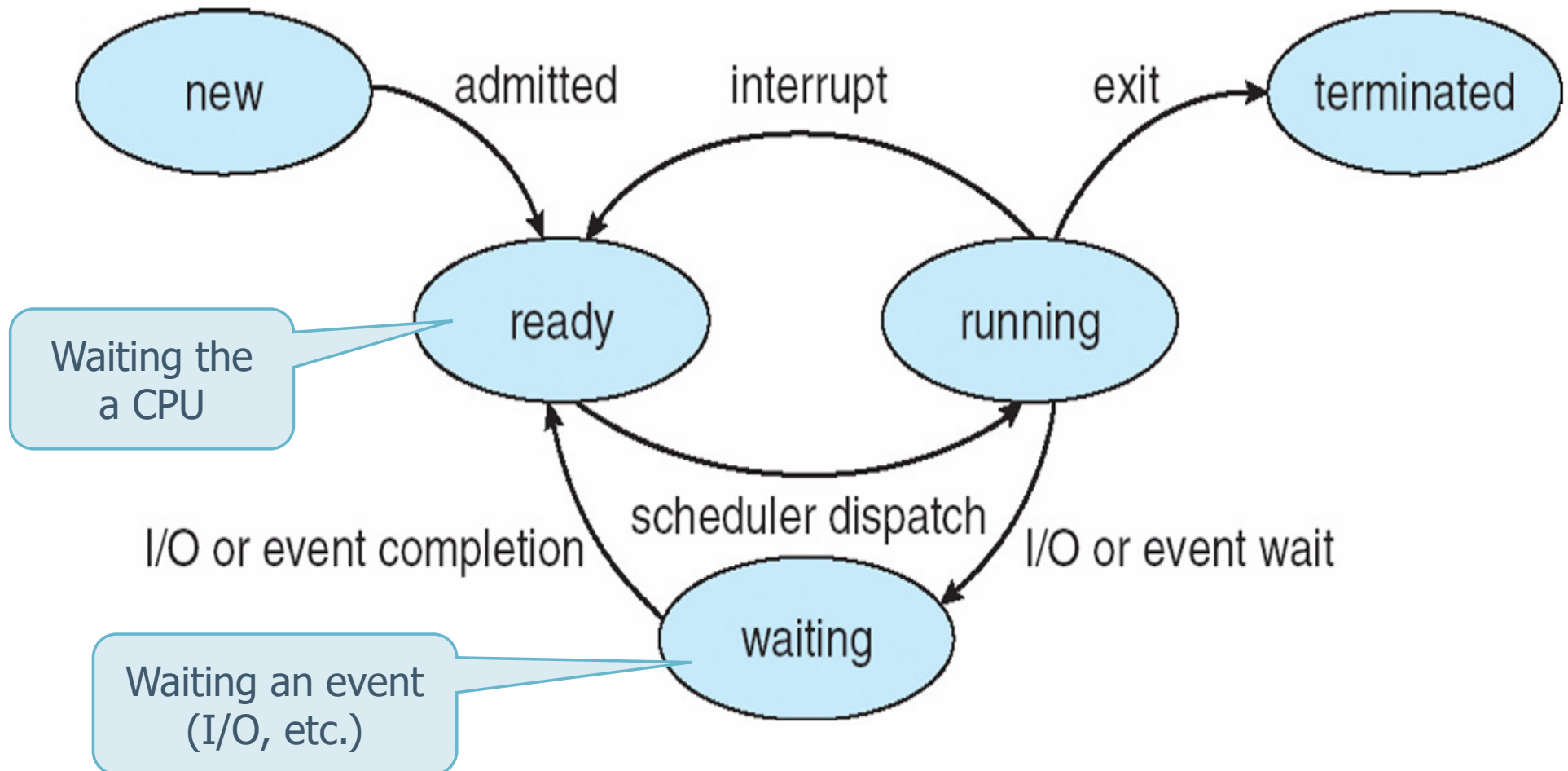
pointer	process state
process number	
program counter	
registers	
memory limits	
list of open files	
⋮	

Process state

- ❖ During its execution a process change its state
 - **New**: process is created and submitted to the OS
 - **Running**: a CPU is allocated to the process (in execution)
 - **Ready**: logically ready to run, waiting that a CPU is available
 - **Waiting**: for an event or for resources
 - **Terminated**: releases the resource it is using

State diagram

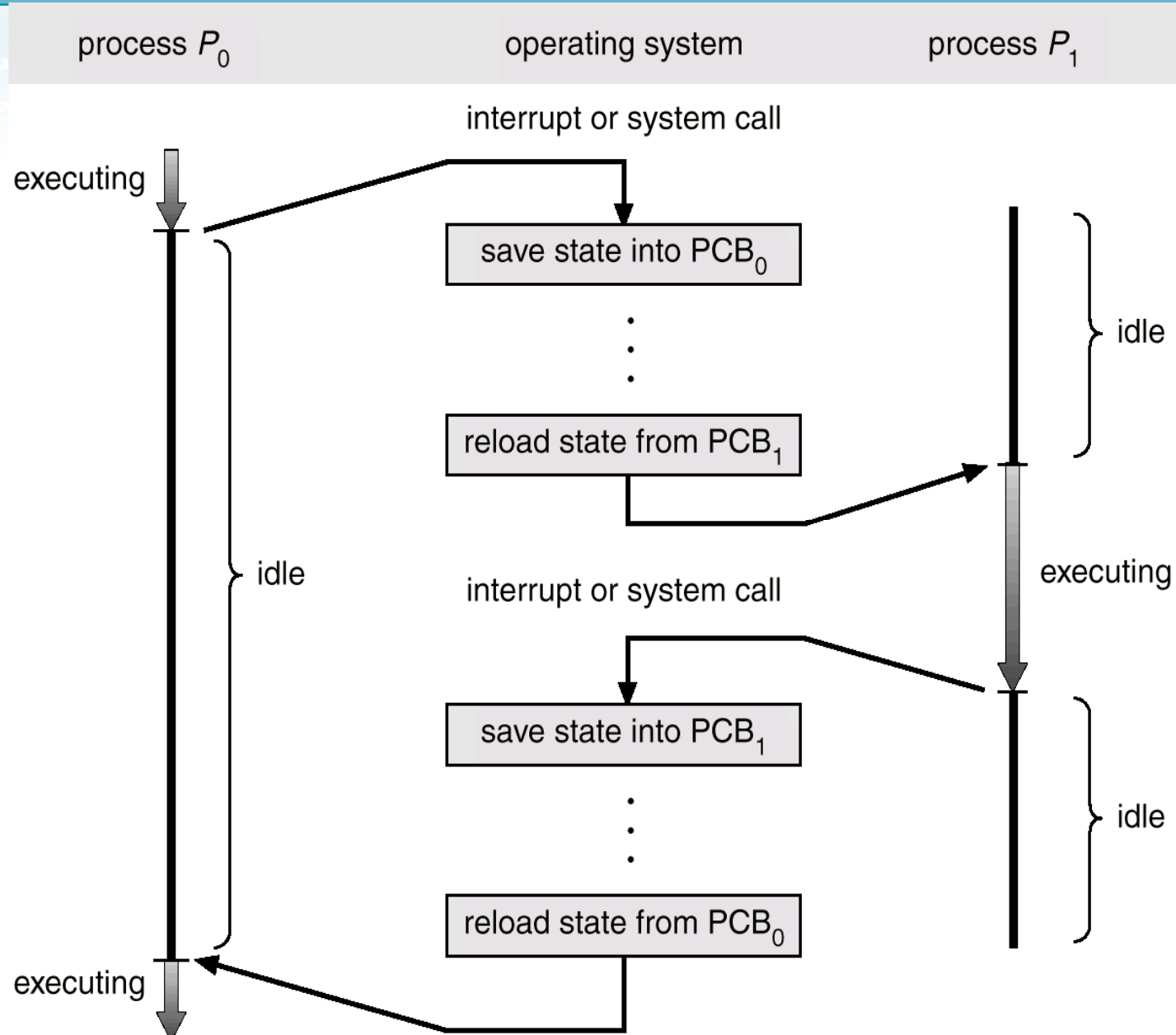
- ❖ The possible state evolution of a process is described by a state diagram



Context switching

- ❖ When the CPU is assigned to another process, the kernel
 - Save the state of the running process
 - Load the state previously saved for the new process
- ❖ The time devoted to the **context switching** is overhead, i.e., time not directly useful for any process
- ❖ The amount of time for context switching is hardware-dependent

Context switching



Process scheduling

- ❖ Multiprogramming aims at maximizing the CPU usage by processes
- ❖ Processes can be classified as
 - I/O-bound
 - Spend more time for I/O than for computation
 - Require short CPU service times
 - CPU-bound
 - Spend more time for computation than for I/O
 - Require long CPU service times

CPU scheduler

- ❖ The **context switching** operations are controlled by **scheduler** of the CPU
 - The goal of the scheduler is to
 - Maximize the CPU usage (by means of the processes)
 - Attempting to satisfy various system-level requests timely (hardware and software interrupts)
 - Ultimately, the scheduler is in charge of
 - Determine when the current process should finish its execution
 - Select the next process to run from the available processes

Continues in
section u09s01