

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>

#define MAXPAROLA 30
#define MAXRIGA 80

int main(int argc, char *argv[])
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;

    for(i=0; i<MAXPAROLA; i++)
        freq[i]=0;

    if(argc != 2)
    {
        printf(stderr, "ERRORE, serve un parametro con il nome del file\n");
        exit(1);
    }
    f = fopen(argv[1], "r");
    if(f==NULL)
    {
        printf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
        exit(1);
    }

    while( fgets( riga, MAXRIGA, f ) != NULL )
```



Processes

Shell commands for process management

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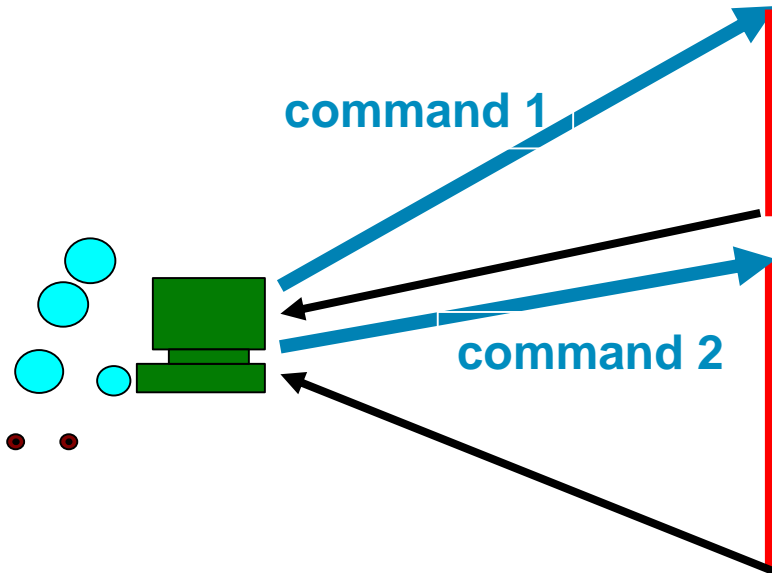
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Foreground execution

- ❖ The "standard" shell commands
 - Allow executing processes **sequentially**
 - Each process is executed in **foreground**, i.e., using the control terminal



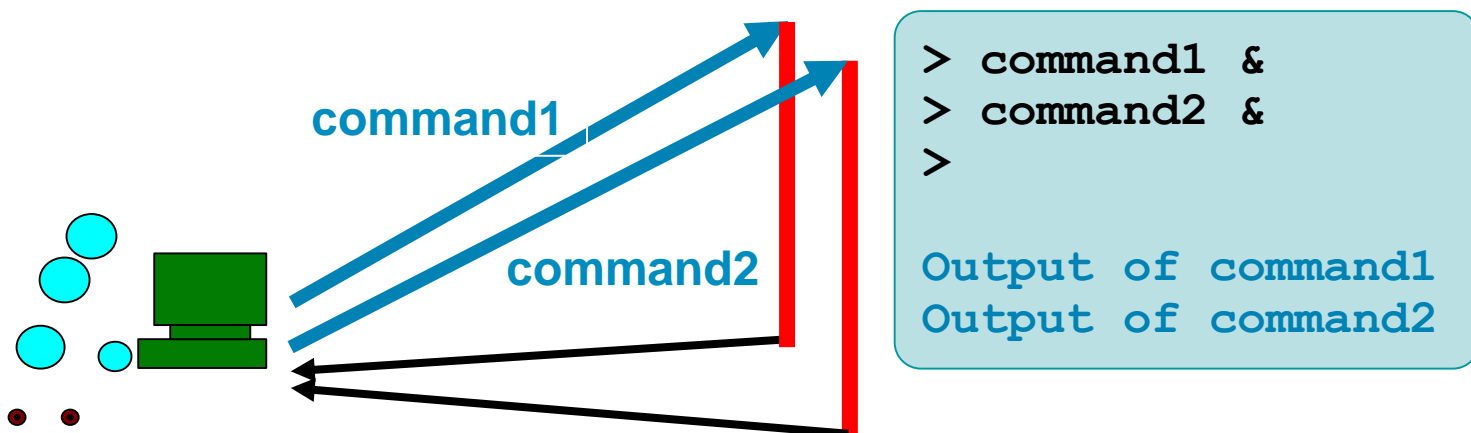
```
> command1
Output of command1

> command2
Output of command2
```

command1; command2; ...
Sequential execution

Background execution

- ❖ The shell interpret character & as an indication to run the command in **background**
 - The process is executed in concurrency with the shell. It loses the control terminal input
 - The shell outputs immediately a new prompt
 - It is possible to run several processes in parallel



Commands for processes

- ❖ There are two main commands to view the status of processes
 - The command **ps** (process status of active process)
 - Lists active processes and related details
 - Without options (default) prints (in a compact format) the status of the processes with the same user ID of the user from which the command is executed

The shell is the parent of all the shell commands and the related processes

Process status commands

➤ ps <options>

- -a Lists the processes of all system users
- -u Prints more detailed information (resident size, virtual size, etc.)
- -u <user> Shows only the <user> processes
- -x Adds to the list the processes that do not have a control terminal (e.g., daemon)
- -e (or -A) Lists all processes running in the system
- -f Extended format
- r (not -r) Shows only the "running" processes

Process status commands

➤ Command **top**

- Display and updates information about the system used resources, and the active processes

```
user@mahine:~/ $ top
```

```
top - 10:26:58 up 57 min, 3 users, load average: 0.00, 0.01, 0.05
Tasks: 152 total, 2 running, 150 sleeping, 0 stopped, 0 zombie
%Cpu(s): 4.0 us, 0.6 sy, 0.4 ni, 93.5 id, 1.4 wa, 0.0 hi, 0.0 si, 0.0 st
KiB Mem: 8177092 total, 1382976 used, 6794116 free, 174096 buffers
KiB Swap: 10482684 total, 0 used, 10482684 free. 544664 cached Mem
```

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND
1821	user	20	0	1297200	198644	39328	S	65.6	2.4	1:59.62	compiz
1302	root	20	0	326708	101316	17712	S	13.1	1.2	0:23.63	Xorg
1	root	20	0	33648	3028	1492	S	0.0	0.0	0:00.78	init
2	root	20	0	0	0	0	S	0.0	0.0	0:00.00	kthreadd
3	root	20	0	0	0	0	S	0.0	0.0	0:00.01	ksoftirqd/0
4	root	20	0	0	0	0	S	0.0	0.0	0:00.00	kworker/0:0

```
...
```

kill command

- ❖ **kill** allows sending signal from the shell
- ❖ **Format**
 - **kill [-sig] pid**
 - Sends signal **sig** to process with PID=**pid**
 - Option **sig** indicates the signal code
 - **pid** is the process identifier (PID) of the target process

kill command

- ❖ A signal **sig** can be indicated by means of its name or by its corresponding number
 - The list of the available signals can be obtained using the "-l" option
 - `SIGKILL = KILL = 9`
 - `SIGUSR1 = USR1 = 10`
 - `SIGUSR2 = USR2 = 12`
 - `SIGALRM = ALRM = 14`
 - etc.
 - The default signal of **kill** is **SIGTERM** (or **TERM**), the standard termination command

kill command

❖ Examples

- `kill -l`
- `kill -9 10234`
- `kill -SIGKILL 10234`
- `kill -KILL 10234`

List available signals

Three commands to terminate process with PID 10234

❖ Shell command `killall` terminates all process with a specified name

- `killall -9 name`
- Useful to terminate all processes generated by the same program avoiding to specify their PIDs